#### Speculative Optimizations without Fear

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# Section 1

## Context

#### Our work

Just-in-time (JIT) compilation is essential to efficient dynamic language implementations.

(Javascript, Lua, R... Java)

There is a blind spot in our formal understanding of JITs: speculation.

We present a language design to study speculative optimizations and prove them correct.







#### Profiling



- + High/Low languages
- + Dynamic code generation/mutation



- JITs: Profiling
  - + High/Low languages
  - + Dynamic code generation/mutation
  - + Speculation



JITs: Profiling

- + High/Low languages
- + Dynamic code generation/mutation
- + Speculation and bailout

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- high- and low-level languages (or multi-tiers, etc.)
- $\bullet\,$  dynamic code generation  $+\,$  mutation
- speculation and bailout

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What about speculation?

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What about **speculation**? This work.

#### What do we want to know?

Speculation requires keeping bailout data.

How should optimizations maintain/transform bailout data? (inlining is tricky)

Does the presence of checkpoint restrict optimizations? (hoisting writes or IO is tricky)

When an assumption fails, how much of the other optimizations can keep? (non-stack-order is tricky)

How should practitioners reason about correctness?



Harper's Weekly cartoon of February 11, 1865.<sup>8</sup>

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a single bytecode language

• speculative optimization and bailout a checkpoint instruction

$$\begin{array}{ll} F_{fun}(c) \rightarrow & \\ V_{tough} \rightarrow & \\ & L_0: & \text{var } o = 1 \\ & L_1: & \text{print } c + o \\ & V_{luck} \rightarrow & \\ & L_0: & \text{assume } c = 41 \text{ else } F_{fun}.V_{tough}.L_1 \ [c = c, o = 1] \\ & L_1: & \text{print } 42 \end{array}$$

### Contribution

A language design to model speculative optimization: Sourir

A kit of correct program transformations and optimizations

A methodology to reason about correct speculative optimizations

# Section 2

#### Sourir

#### A simple bytecode language

i ::= | se | x[se] | **length**(se) | primop (se\*) read x stop

#### Versions

# $\begin{array}{ll} P & ::= (F(x^*) \to D_F)^* \mbox{ program: a list of named functions} \\ D_F & ::= (V \to I)^* \mbox{ function definition: list of versioned instruction streams} \\ I & ::= (L:i)^* \mbox{ instruction stream with labeled instructions} \end{array}$

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#### Checkpoints

Checkpoint: guards + bailout data.

assume 
$$c = 41$$
 else  $F_{fun}$ .  $V_{tough}$ .  $L_1$  [ $c = c, o = 1$ ]

Guards: just a list of expressions returning booleans.

Bailout data:

- where to go:  $F_f.V_w.L_I$
- in what state:  $[x_1 = e_1, \ldots, x_n = e_n]$
- (plus more: see inlining)

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Not a branch. (inlining) Checkpoints simplify optimizations...and correctness proofs!

#### **Critical version**











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## Section 3

## Formalization

#### Execution: Operational semantics

Configurations:

$$C ::= \langle P \, I \, L \, K^* \, M \, E \rangle$$

Actions:

$$A ::= \operatorname{read} \operatorname{lit} | \operatorname{print} \operatorname{lit} \qquad A_{\tau} := A | \tau \qquad T ::= A^*.$$

Reduction:

$$C_1 \xrightarrow{A_{\tau}} C_2 \qquad \qquad C_1 \xrightarrow{T} C_2$$

## Equivalence: (weak) bisimulation

Relation *R* between the configurations over  $P_1$  and  $P_2$ .

R is a weak **simulation** if:



*R* is a weak **bisimulation** if *R* and  $R^{-1}$  are simulations.

Version invariant: All versions of a function are equivalent. (Necessary to replace the active version)

Bailout invariant: Bailing out **more** than necessary is correct. (Necessary to add new assumptions)

## Section 4

Optimizations

#### Branch pruning - from the kit

 $V_{base} \rightarrow$ 



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 $\begin{array}{ll} L_1: & \text{branch } tag = INT \ L_{int} \ L_{nonint} \\ L_{int}: & \dots \\ L_{nonint}: & \dots \end{array}$ 

$$V_{opt} \rightarrow \begin{cases} L_0 : & \text{assume } tag = INT \text{ else } F.V_{base}.L_1 \ \delta \\ L_1 : & \text{branch } tag = INT \ L_{int} \ L_{nonint} \\ L_{int} : & \dots \\ L_{nonint} : & \dots \end{cases}$$

Checkpoint + guard inserted

Bailout invariant!

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constant folding

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$$V_{opt} \rightarrow$$
 $L_0:$  assume  $tag = INT$  else  $F.V_{base}.L_1 \delta$   
 $L_{int}:$  ...

unreachable code elimination

## Inlining

# Inlining

main (inlined)main(base)sizeassume 
$$obj \neq$$
 nil else  $\xi \langle F_{main}. V_{base}. L_{ret} size [vec = vec] \rangle$ 

#### Conclusion

All you need for speculation: versions + checkpoints.

Future work: bidirectional transformations.

Thanks! Questions? Magnus O. Myreen. Verified just-in-time compiler on x86. In Principles of Programming Languages (POPL), 2010.